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3 A force reflective master-slave system for minimally invasive surgery

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4 Dual use applications of Wright Laboratory Avionics Technologies to computer assisted minimally invasive surgery (CAMIS)

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5 Controlling miniature robotic systems in minimally invasive surgery*Wapler, M.; Neugebauer, J.;*

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Pages:711 - 716 vol.1

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[\[Abstract\]](#) [\[PDF Full-Text \(236 KB\)\]](#) IEE CNF**7 Force controlled and teleoperated endoscopic grasper for minimally invasive surgery-experimental performance evaluation***Rosen, J.; Hannaford, B.; MacFarlane, M.P.; Sinanan, M.N.;*

Biomedical Engineering, IEEE Transactions on , Volume: 46 , Issue: 10 , Oct. 1999

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[\[Abstract\]](#) [\[PDF Full-Text \(444 KB\)\]](#) IEEE JNL**8 Applications of micromechatronics in minimally invasive surgery***Tendick, F.; Sastry, S.S.; Fearing, R.S.; Cohn, M.;*

Mechatronics, IEEE/ASME Transactions on , Volume: 3 , Issue: 1 , March 1998

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13 Sensors and devices to enhance the performances of a minimally invasive surgery tool for replicating surgeon's haptic perception of the manipulated tissues*Scilingo, E.P.; De Rossi, D.; Bicchi, A.; Iacconi, P.;*

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2 Web component development for satellite imagery internet service system

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